## **Sperry Marine**

### NORTHROP GRUMMAN

# **NAVIGAT X MK 1**



Microprocessor Controlled Digital Gyrocompass System

## **Design and Standard Features**

#### **OVERVIEW**

With a watchful eye on the demands made on navigation and ship control technology emerging from the 21st Century, Northrop Grumman Sperry Marine has created the NAVIGAT X MK 1 Digital Gyrocompass System.

Ship's cables are connected directly to terminals within the gyrocompass housing, greatly facilitating installation. All electronic components are plug-in modules, thus providing fast and easy service. Digital heading information is derived as an absolute value from a 13-bit shaft encoder. The NAVIGAT X MK 1 has a control and display unit installed in the front access cover. When required, the control and display unit can be removed from the access cover and installed at a location (e.g. bridge console) remote from the gyrocompass.

### **STANDARD FEATURES**

- Comprises one single unit
- Control and display unit in front cover with 4-digit heading display and 6 operating keys
- Easy to install and easy to service
- High-speed follow-up system 100°/sec
- Type approved rate-of-turn output
- Automatic static north speed error correction
- Highly accurate digital heading data transmission by shaft encoder
- Self-synchronizing repeater compasses
- ±180° electronic alignment error correction in setup program
- Will drive a maximum of 12 analogue repeaters
- 180° heading offset function for shuttle vessels
- Automatic emergency power changeover and status alarm

- 7 independent serial outputs RS 422, IEC 61162-1 and IEC 61162-2
- 2 dependent 6 steps/° heading outputs (0.5 A)
- Complies with IMO regulations A.424(IX), A.694(17), A.821(19) - HSC (High Speed Craft) and ISO 8728.
- Outputs to Navigation Data Printer:
  - Heading
  - Heading source gyro/magnetic
  - Rudder angles of two independent rudders
- Twin rotors and liquid damping system eliminates latitude error
- High Mean Time Between Failures (MTBF) of 40.000 hours and low power consumption
- All repeater compasses with serial interface
- Gyro system remains north stabilized during power interruptions of up to 3 minutes
- Single point suspension of the gyrosphere container eliminates the well-known adverse effects associated with gimbals.
- Monitoring and alarm functions for all voltages, gyroscope current and followup system (gyrosphere current, temperature, elapsed operation time)

The unique method of supporting the wellproven Sperry Marine gyrosphere by means of mere buoyancy ensures north stabilization during short power failures.

A special version, NAVIGAT X MK 1 HSC, is available to meet the demands of high-speed craft (HSC). Here, the unique centering pin retaining arrangement for the gyrosphere is mounted in an additional gimbal system, which allows the NAVIGAT X MK 1 Mod 7 gyrocompass an almost unlimited freedom of roll and pitch (±90°).

### **TYPE APPROVAL**

NAVIGAT X MK 1 has been type approved by Germanischer Lloyd (GL) in accordance with the Marine Equipment Directive (MED) 96/98/EC (Wheelmark) and fulfills IMO Resolutions A.424(XI) and A.694(17) as well as IEC 61162. The NAVIGAT X MK 1 HSC has been type approved to the High-Speed Craft Code by Germanischer Lloyd (GL) in accordance with the Marine Equipment Directive (MED) 96/98/EC (Wheelmark).

The rate-of-turn outputs of NAVIGAT X MK 1 and NAVIGAT X MK 1 HSC have been type approved by Germanischer Lloyd (GL) in accordance with the Marine Equipment Directive (MED) 96/98/EC (Wheelmark) and also fulfills IMO resolution A.526(13).

### **PERFORMANCE**

Linear mean settle point

error (RMS): ≤0.1° secant latitude

Static

error (RMS): ≤0.1° secant latitude

Dynamic

error (RMS): ≤ 0.4° secant latitude

Performance in accordance with IMO A.694(17), IMO A.821(19), ISO 8728 and ISO 16328(2001).

### **FREEDOM OF ROLL & PITCH**

NAVIGAT X MK 1 Mod 7 ±90° NAVIGAT X MK 1 Mod 10 ±40°

### **POWER REQUIREMENTS**

24 VDC (18 V to 36 V) and / or 115/230 VAC ± 10% 50 Hz / 60 Hz

The single-unit gyrocompass includes automatic swtichover to 24 V emergency power supply in accordance with GMDSS Rules

### OPERATIONAL DATA

Ambient temperature range

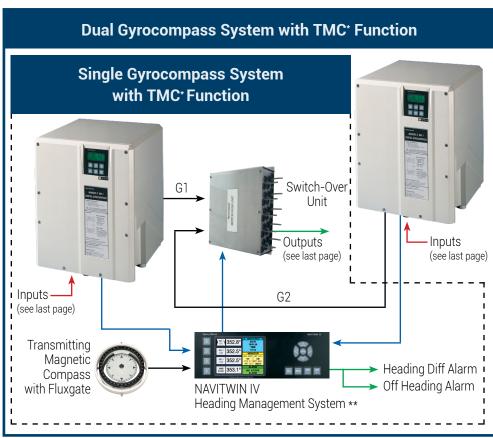
Operation: -10°C to +55°C Storage: -25°C to +70°C

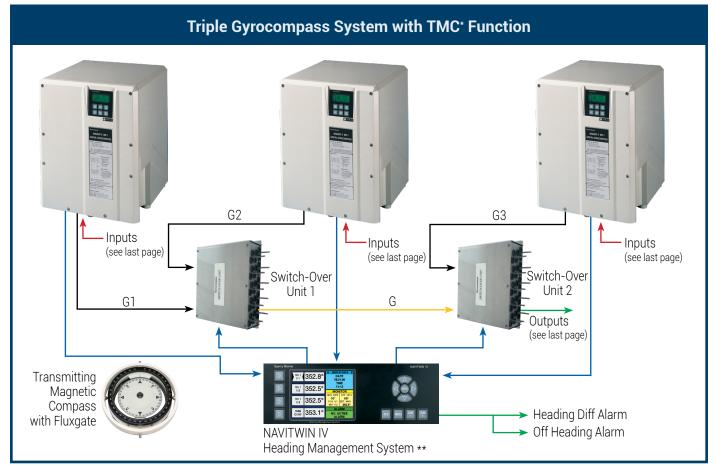
(without supporting fluid)

Settling Time: < 3 hours Gyrocompass follow-up rate: 100°/sec Heading Display: digital with 4 digits

### **System Configurations**







<sup>\*</sup>Transmitting Magnetic Compass. In TMC systems, the NAVITWIN IV Heading Management System provides an independent back-up magnetic heading source for distribution to autopilots, repeaters, radars and other peripheral appliances when required.

<sup>\*\*</sup> With selectable and programmable automatic heading takeover in accordance with Grounding Avoidance System (DNV NAUT OC and AW)

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### **OPERATIONAL DATA**

Power Failure Alarm: visible and audible and

potential-free contact, max. 30 VDC / 1.0 A, max. 125 VAC / 0.5 A

Mean time between

failure: 40,000 hours (MTBF)

North speed error

correction: automatic or manual

Built-in test equipment: standard

### POWER CONSUMPTION

	DC	AC
Start-up:	80W	125VA
Operation:	45W	75VA
Each analogue repeater:	6W	6VA
Each universal digital		
repeater:	5W	5VA

### PROTECTION GRADE

Gyrocompass: IP 23 in accordance

with IEC/EN 60529

### **ENVIRONMENTAL REQ. & EMC**

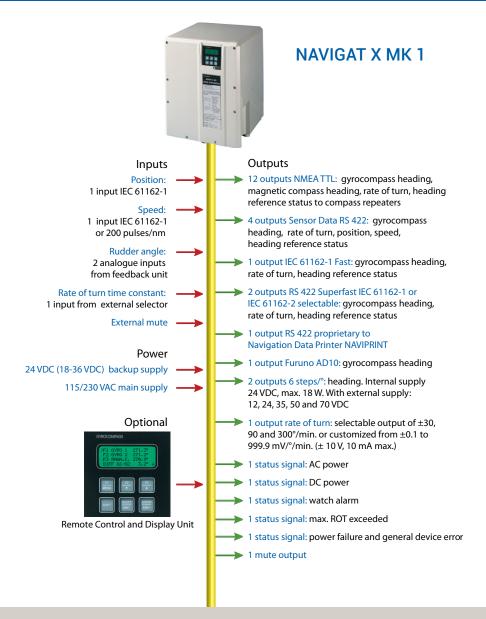
In accordance with EN 60945 (IEC 945 + A1)

Magnetic clearance to:

standard magnetic compass 0.6m steering magnetic compass 0.4m

Reduced magnetic clearance to:

standard magnetic compass 0.3m steering magnetic compass 0.3m



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